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Agile Condor: Scalable High Performance Embedded Computing Architecture

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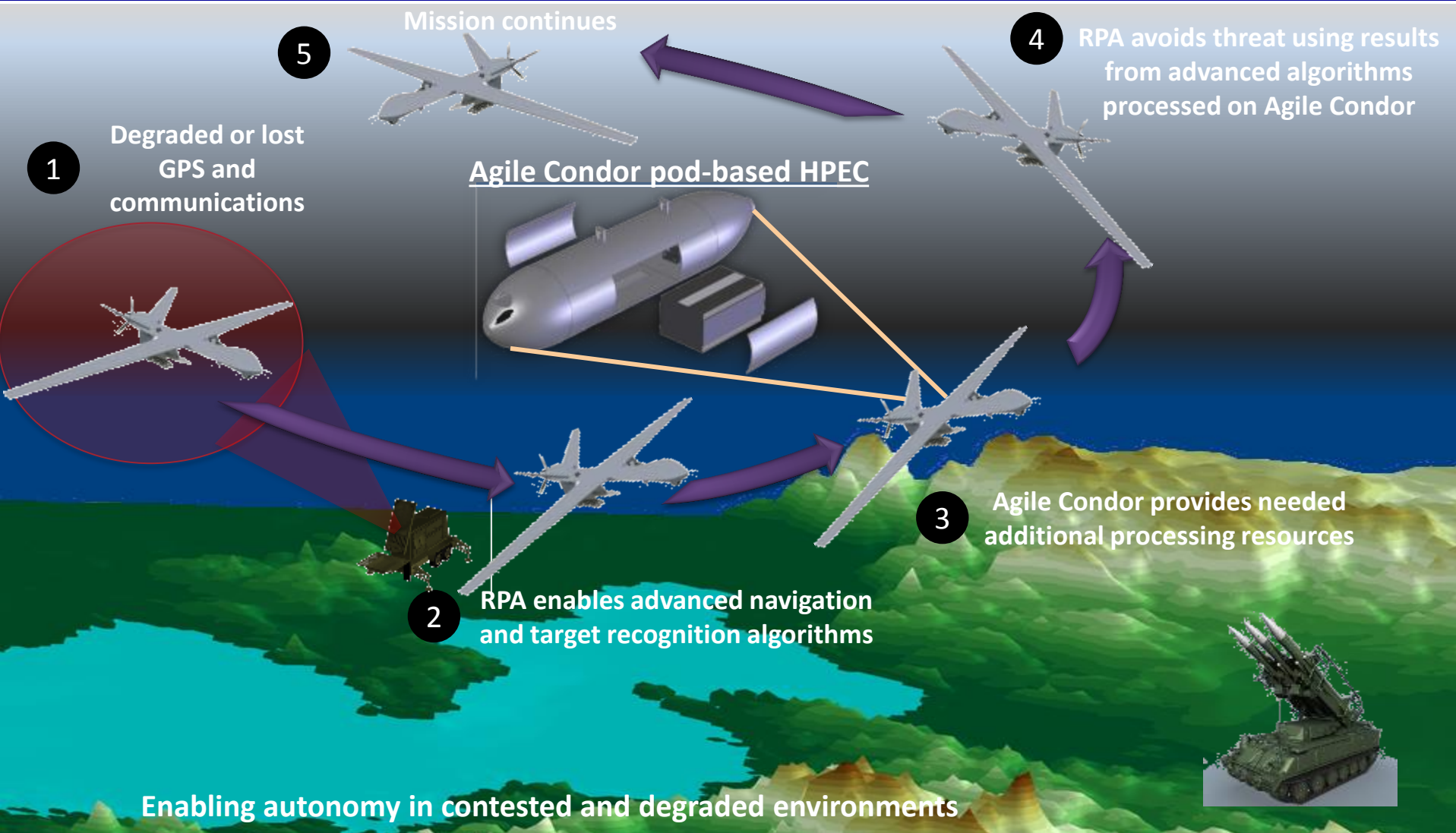
AGILE CONDOR Agenda



- CONOPS- Why Agile Condor?
- System Overview
- Pod and Chassis Design
- Scalability of the system
- AirWASP Processing Framework
- Future Work
- Summary



AGILE CONDOR Operations Concept





AGILE CONDOR Capability Vision



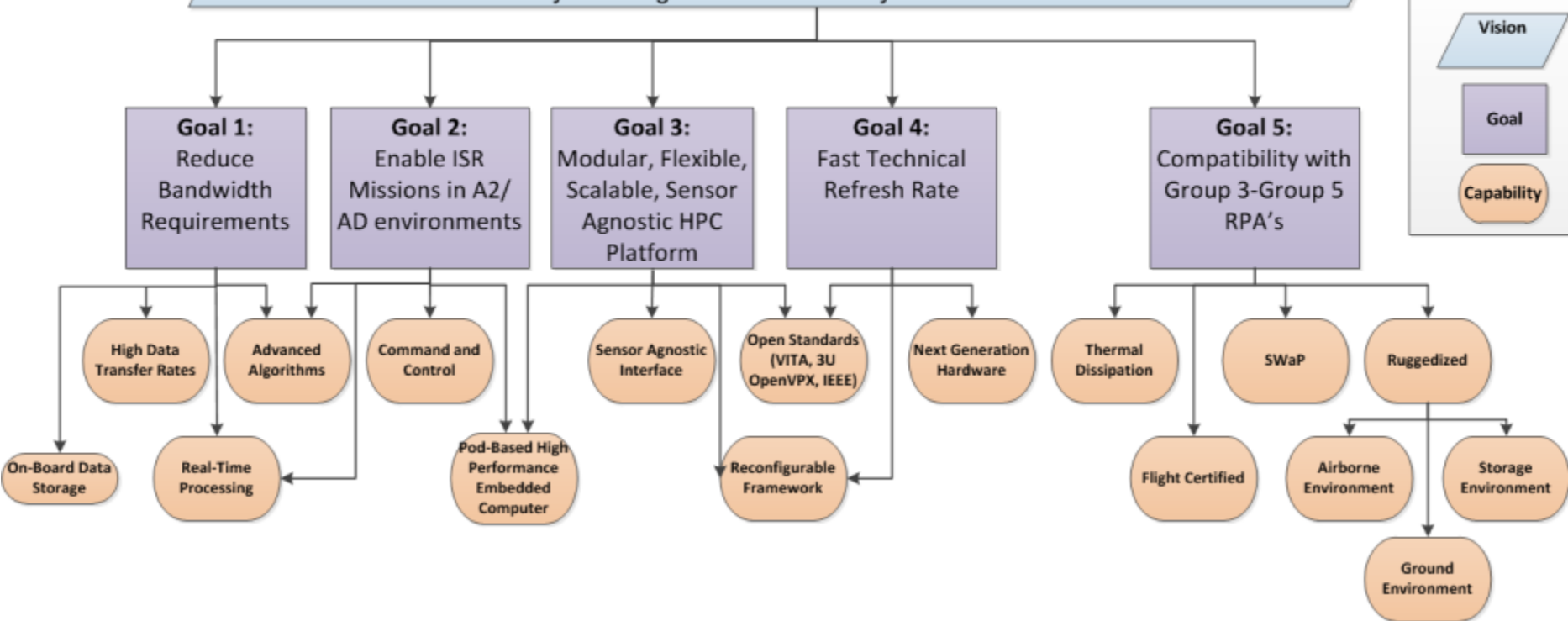
Vision: Increase warfighter effectiveness by enhancing remotely piloted systems capabilities and expanding their capacity to create effects in the battlespace. The initial focus must be on onboard processing of data from sensors to reduce bandwidth required, further enabling human analysts to be more efficient and effective by focusing their efforts on key information.

Legend

Vision

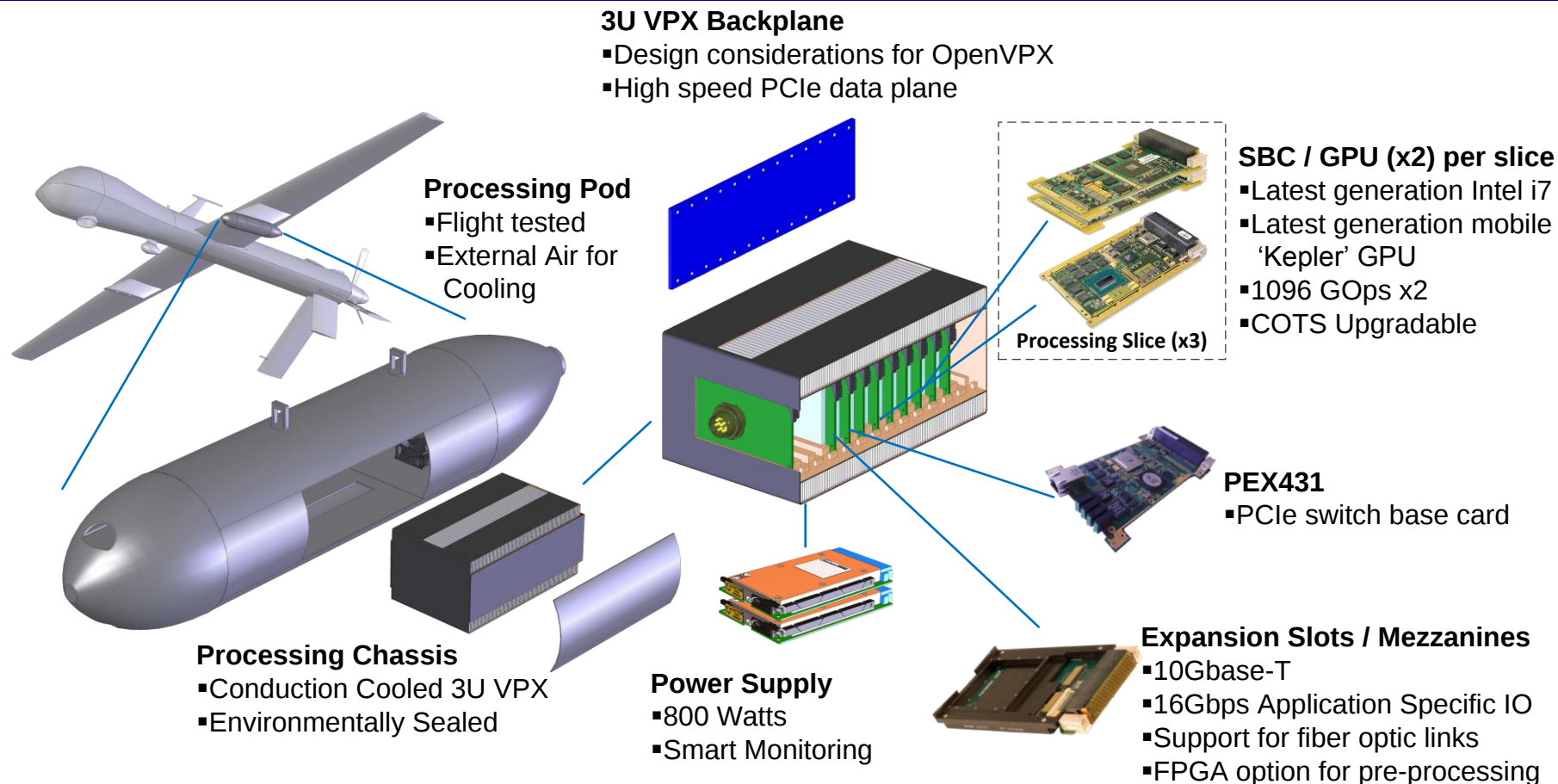
Goal

Capability





AGILE CONDOR System Overview



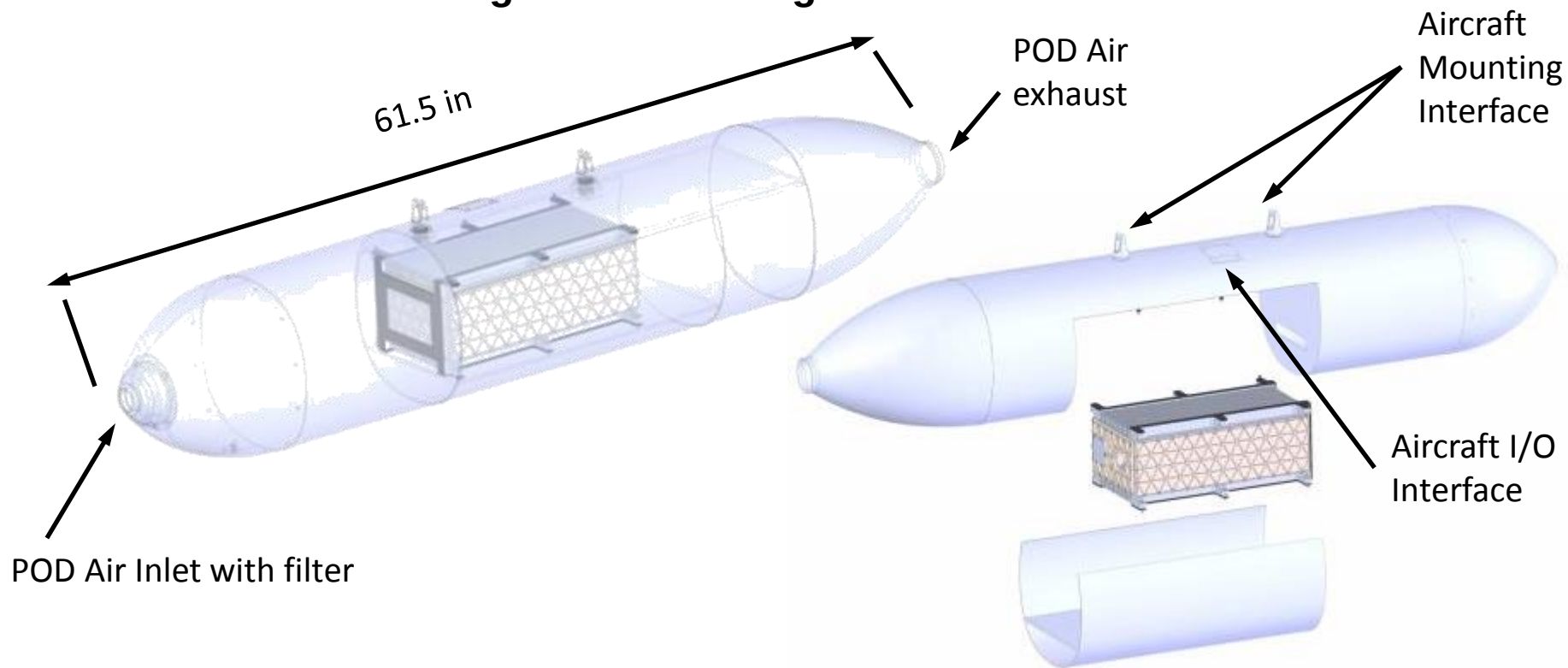
Agile Condor brings distributed high-performance computing closer to the sensor



AGILE CONDOR POD & Chassis

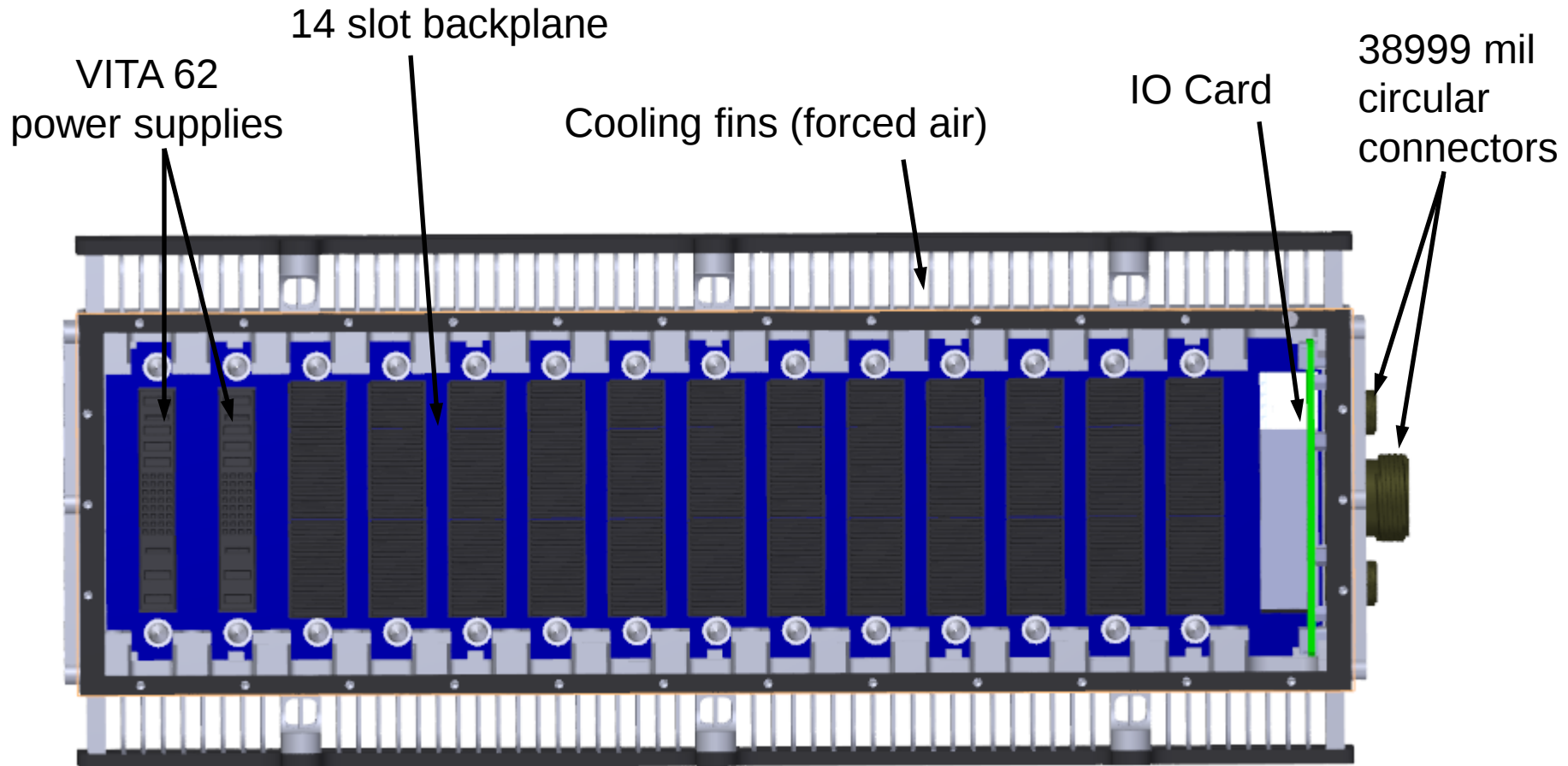


- Existing pod baseline flight certified
- MIL-STD-8591 design for aircraft interface and aerodynamics
- Ambient air cooling thermal management





AGILE CONDOR Chassis Details



14 slot, 3U, VPX Conduction Cooled Chassis



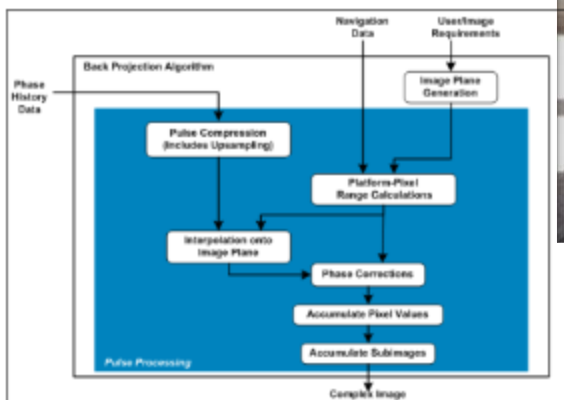
Embedded HPC 2015 Flight Test



- **Embedded real-time experiments**

- **AirWASP**

- FY15 Flight tests (July 2015, Utah)
- 18Tflops – 1400W





A satellite map of the Denver, Colorado area, showing the flight path of the 1993 US Airways Flight 587. The map features a large black circle centered over the city. A blue line, representing the flight path, starts at a yellow dot labeled 'Aircraft Position' near the top edge of the circle, passes through the 'Logan-Cache Airport' (marked with a blue plane icon), and ends at a green house icon labeled 'SDL Headquarters'. The terrain is a mix of green fields, urban areas, and brownish hills. The Google logo is visible in the bottom right corner, and a copyright notice '© 1993' is in the bottom left corner.

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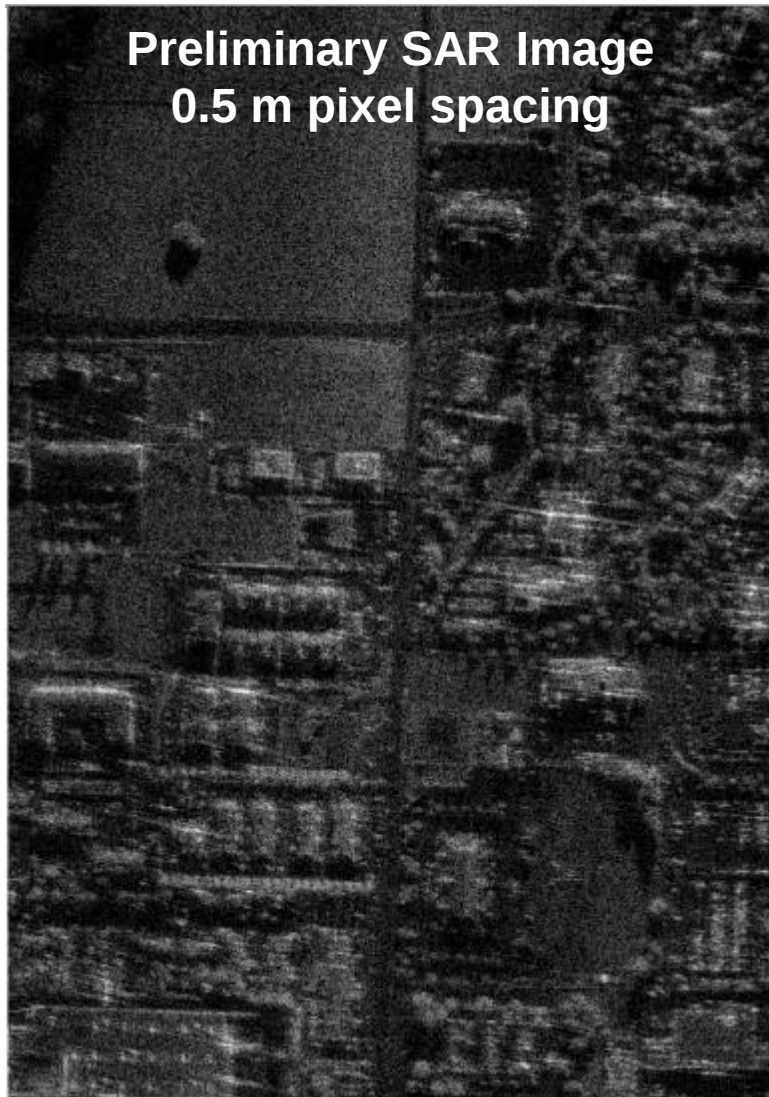




Embedded HPC 2015 Flight Test



Preliminary SAR Image
0.5 m pixel spacing

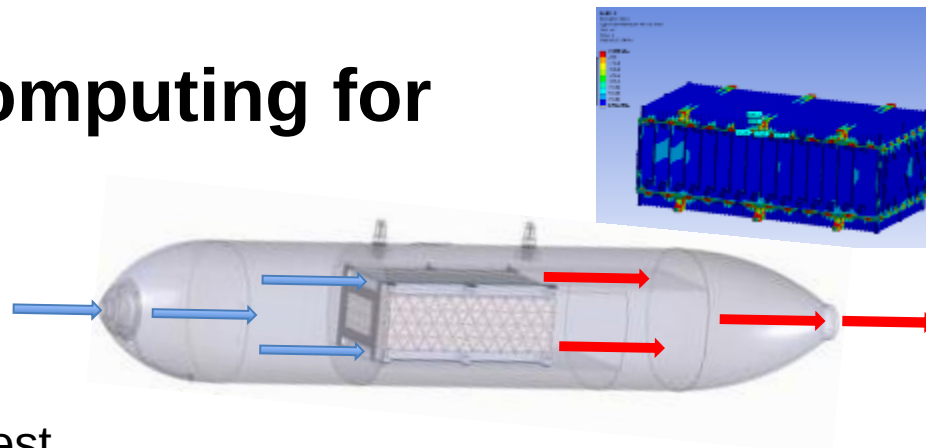




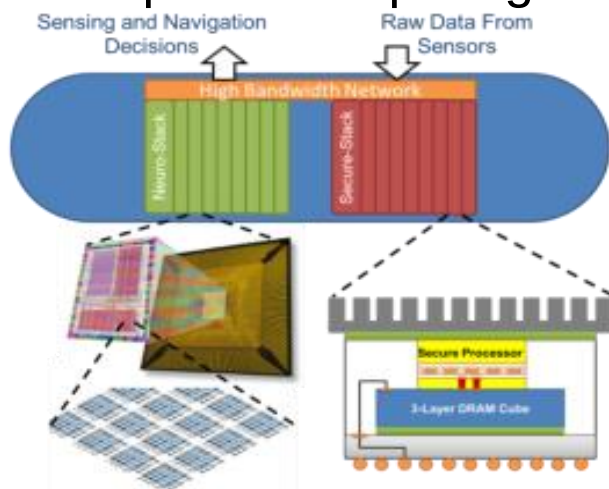
Future Work

•Onboard embedded computing for Autonomous Sensing

- FY16 Embedded HPC Pod
 - 5-10 Tflops ~ 400 W
 - October 2016 Planned Flight Test
- FY18 Secure Processor & Bio-Inspired Computing

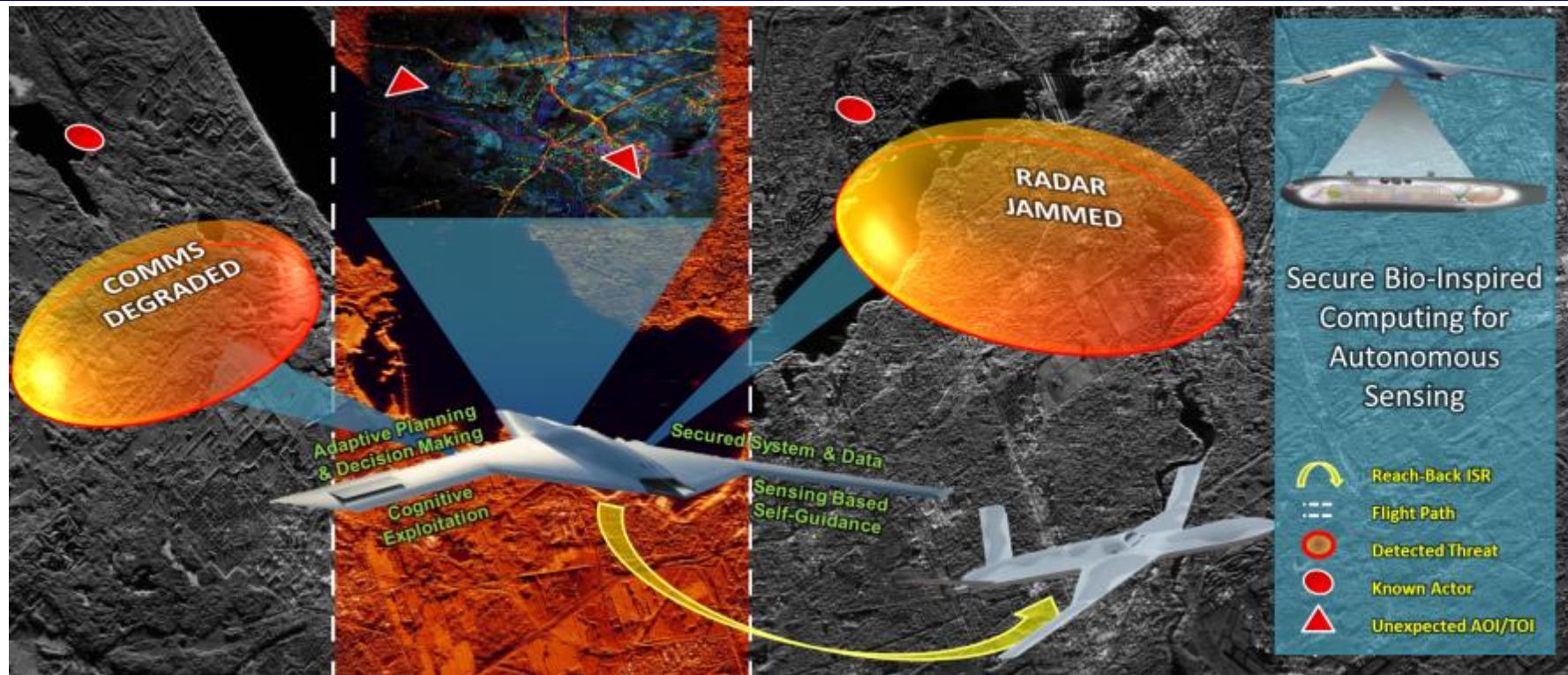


The Agile Condor form factor, power, weight, environmental, and thermal management capability will support Group 3 (e.g. RQ-7 Shadow) to Group 5 (e.g. MQ-9 Reaper) DoD UAS platforms.





Secure Bio-Inspired Computing



Challenges

- Degraded communication links
- Dynamic ISR situations
- Dynamic surface-to-air threats
- Targeted cyber attacks
- GPS jamming

R&D Needs

- Cognitive Exploitation
- Adaptive decision making
- Secured system and data
- Sensing-based self-guidance
- SWaP-efficient on-board comp.

Benefits

- Human-in-the-loop: high situational awareness and performance, reduced comm.
- Human-out-of-the-loop: continue ISR mission, survive unexpected threats.



AGILE CONDOR Summary



- Leader in Embedded HPC technologies
 - First Embedded HPC POD based system (SRC-AFRL, Patent Pending)
 - 5-10 Tflops (400-500 Watts)
- Embedded HPC Flight Tests
 - Provide realistic environment and integration challenges
- Secure Bio-Inspired Computing CRDF
 - 17 TrueNorth small factor boards (Oct-Nov 2015)
 - Increased processing capability (100-1000x) in size, weight and power constrained applications
- Greater system resilience, adaptability, autonomy and intelligence



Questions?

